

Two-component vector wind fields by scanning aerosol lidar

Research Objective:

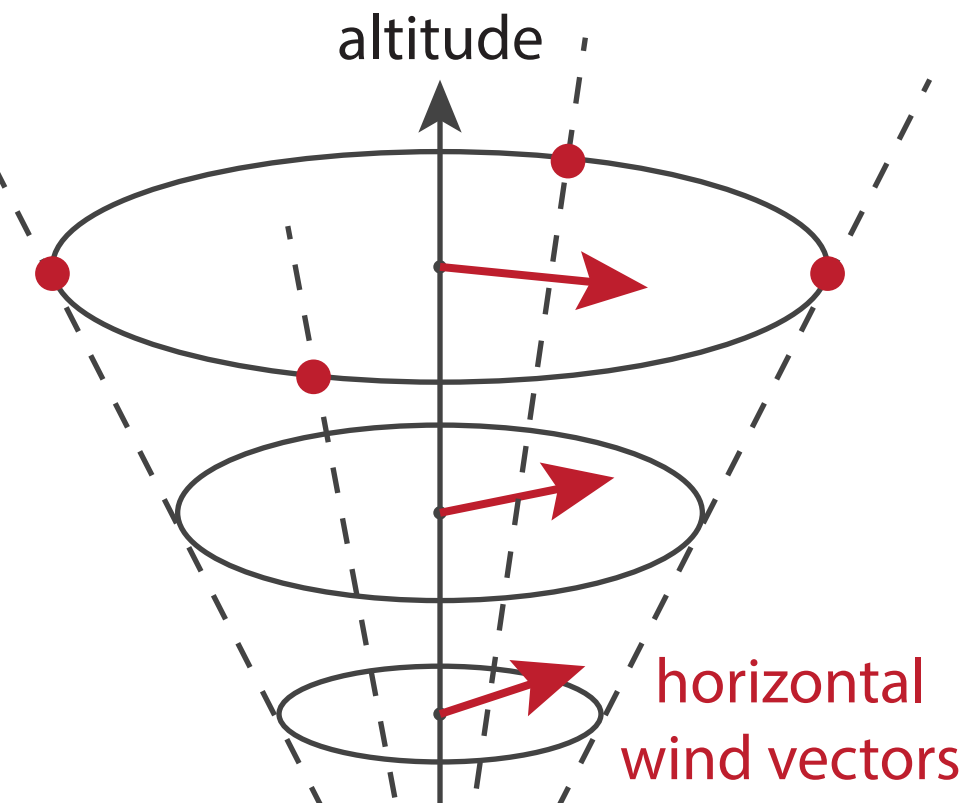
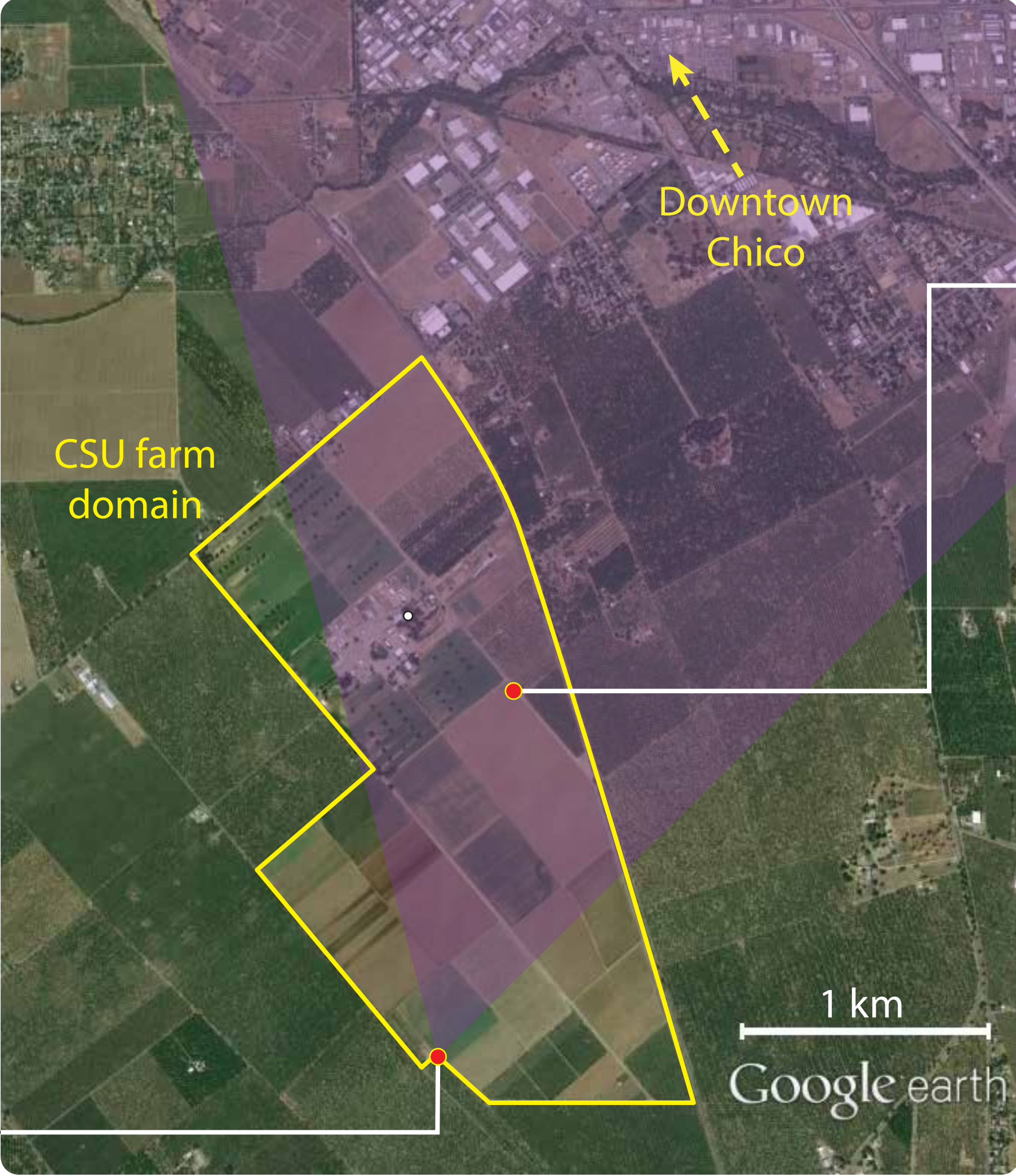
To determine the ability of a quasi-horizontally **scanning eye-safe aerosol lidar** to estimate the **two-component vector wind field** above the reach of traditional meteorological towers.

Phase 1: Temporal Validation

July 1, 2013 to November 25, 2013

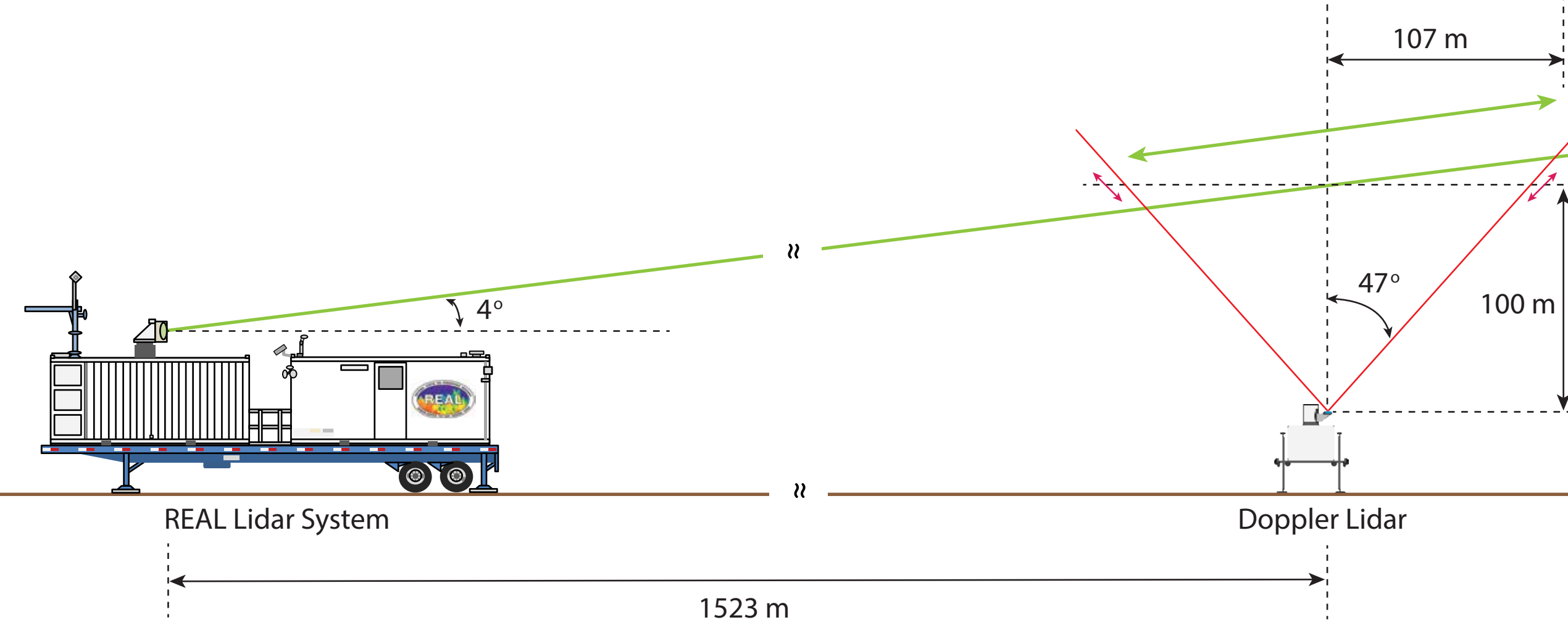
During this phase of the experiment, the **Doppler lidar** was **located 1.52 km from the REAL** in order to provide a time-series of horizontal wind vectors for one point in the REAL scan area (purple shaded region at right). This data enables us to **compare the temporal evolution of the wind at a single point in space**.

The **REAL** is an analog direct-detection elastic **backscatter lidar** at 1.54 μm . It has no Doppler capability. **Wind fields** are determined by application of **motion estimation** algorithms to aerosol backscatter images available every 17 s.

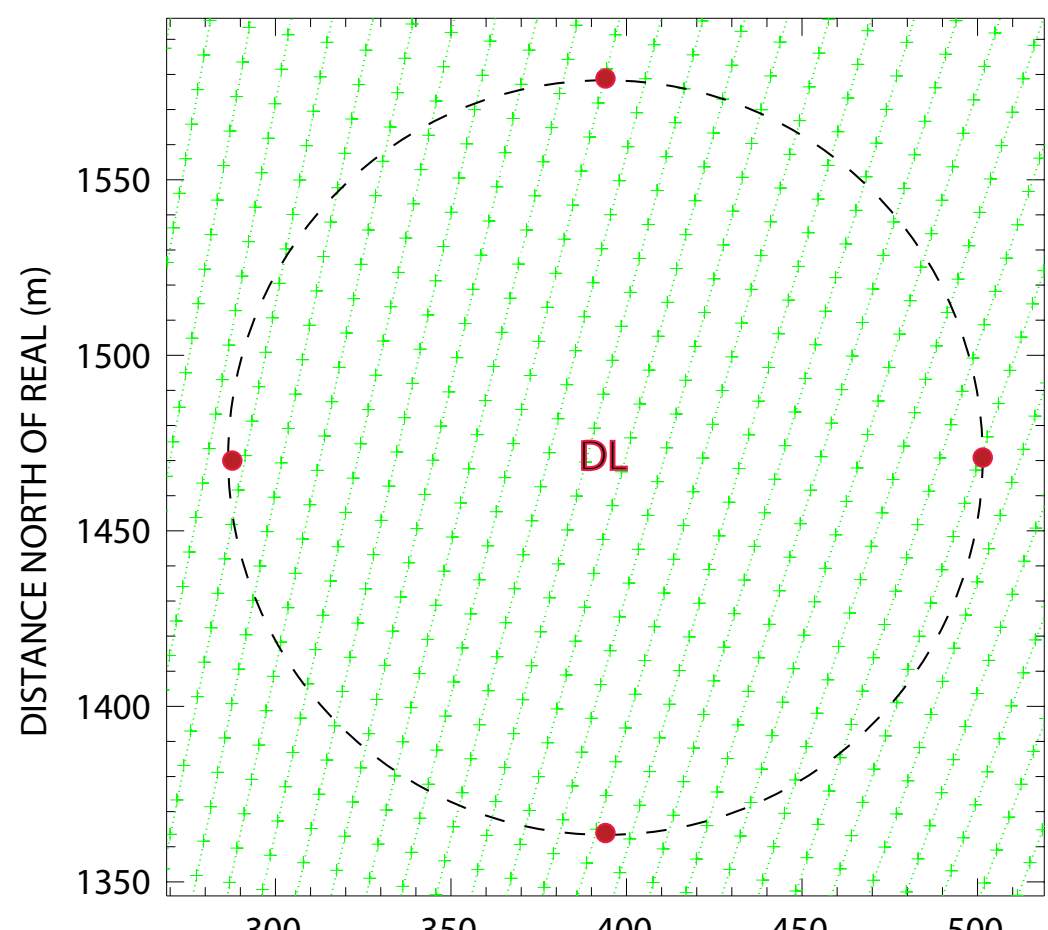


HALO Phototonics Streamline (UK) Doppler lidar for validation

The heterodyne Doppler lidar also operates at 1.5 μm wavelength. From this location, the Doppler lidar observed **vertical profiles of horizontal wind vectors** by using a Doppler beam swinging technique. Horizontal wind profiles were updated every 17 s, with vectors available every 10 m between 30 and 170 m AGL.

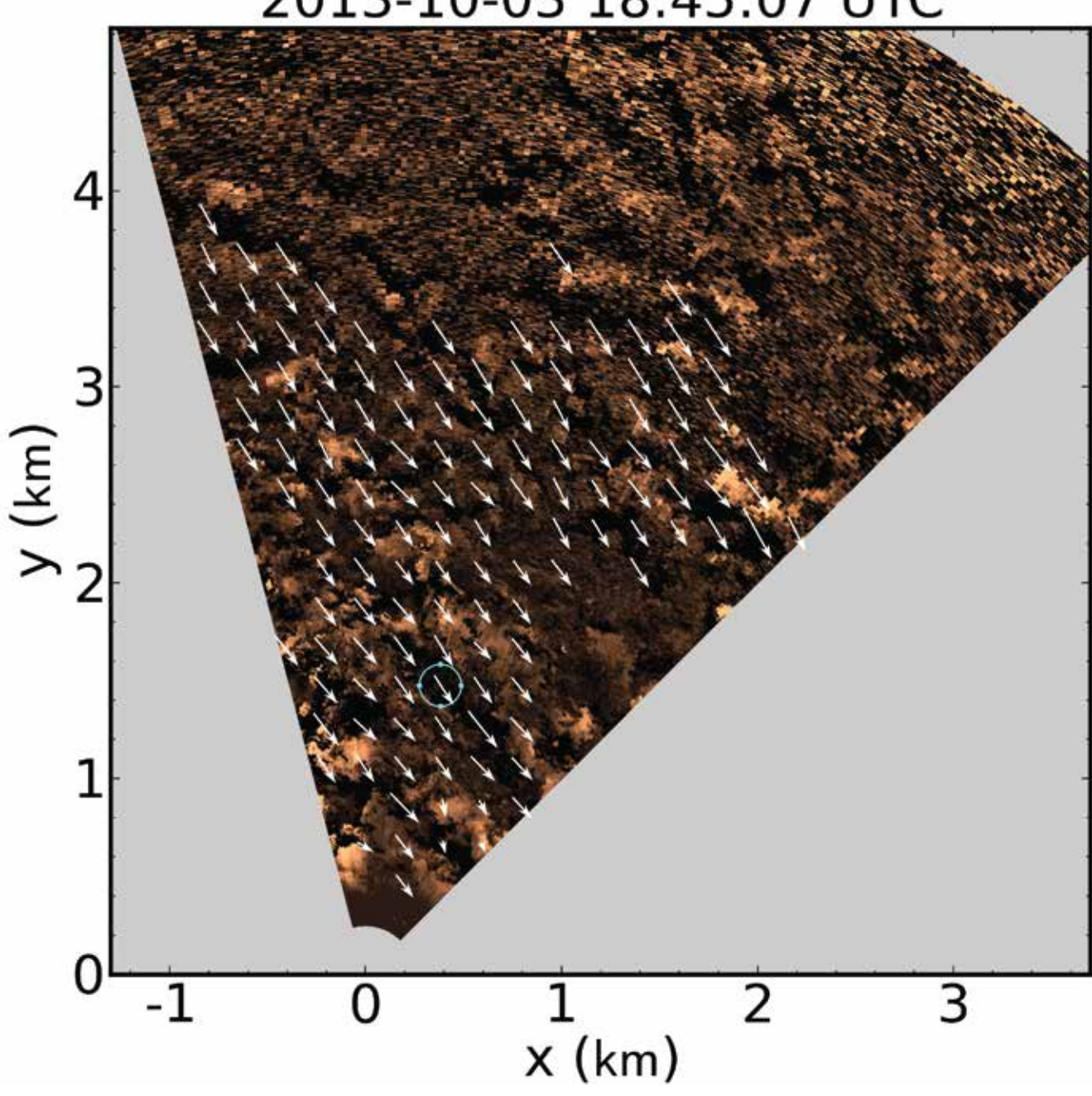


Top-down view of lidar samples at 100 m AGL above the Doppler lidar:
green + REAL backscatter
red • Doppler pulse volume

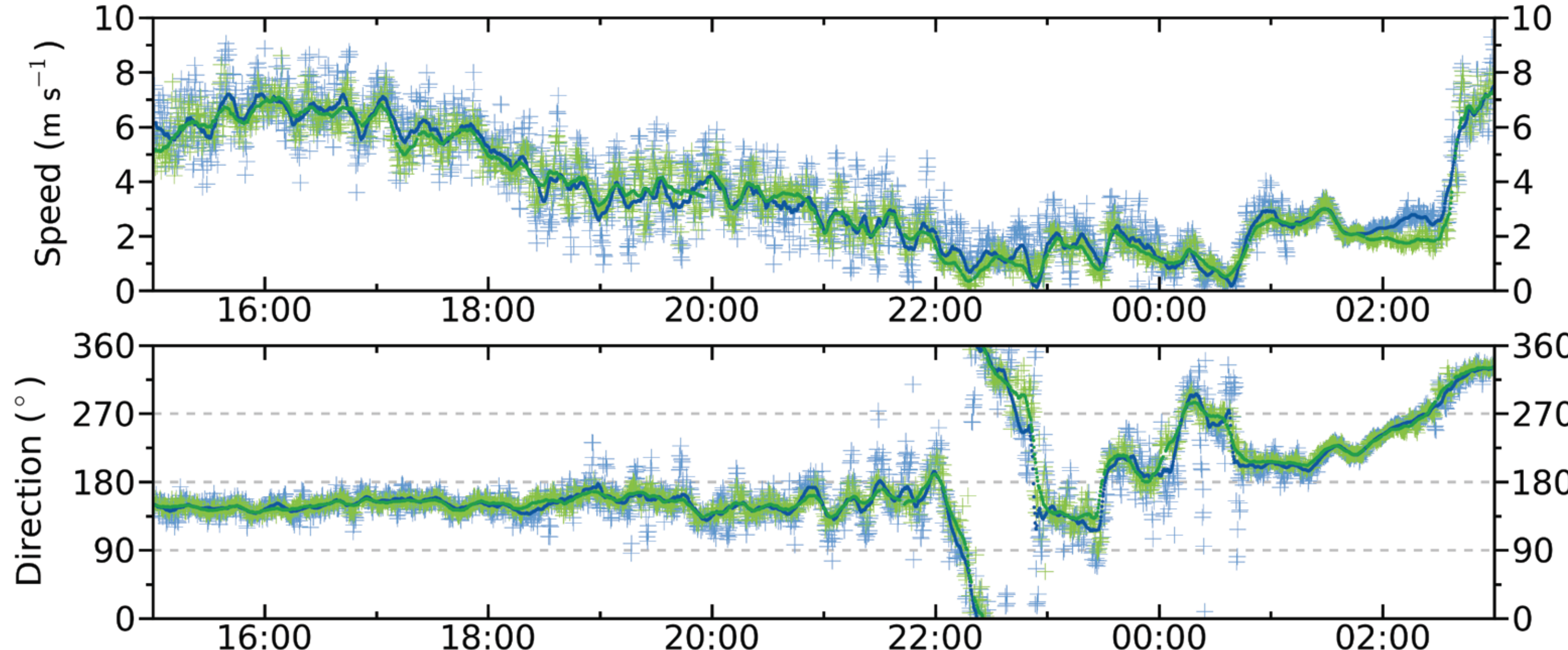


2 motion estimation algorithms

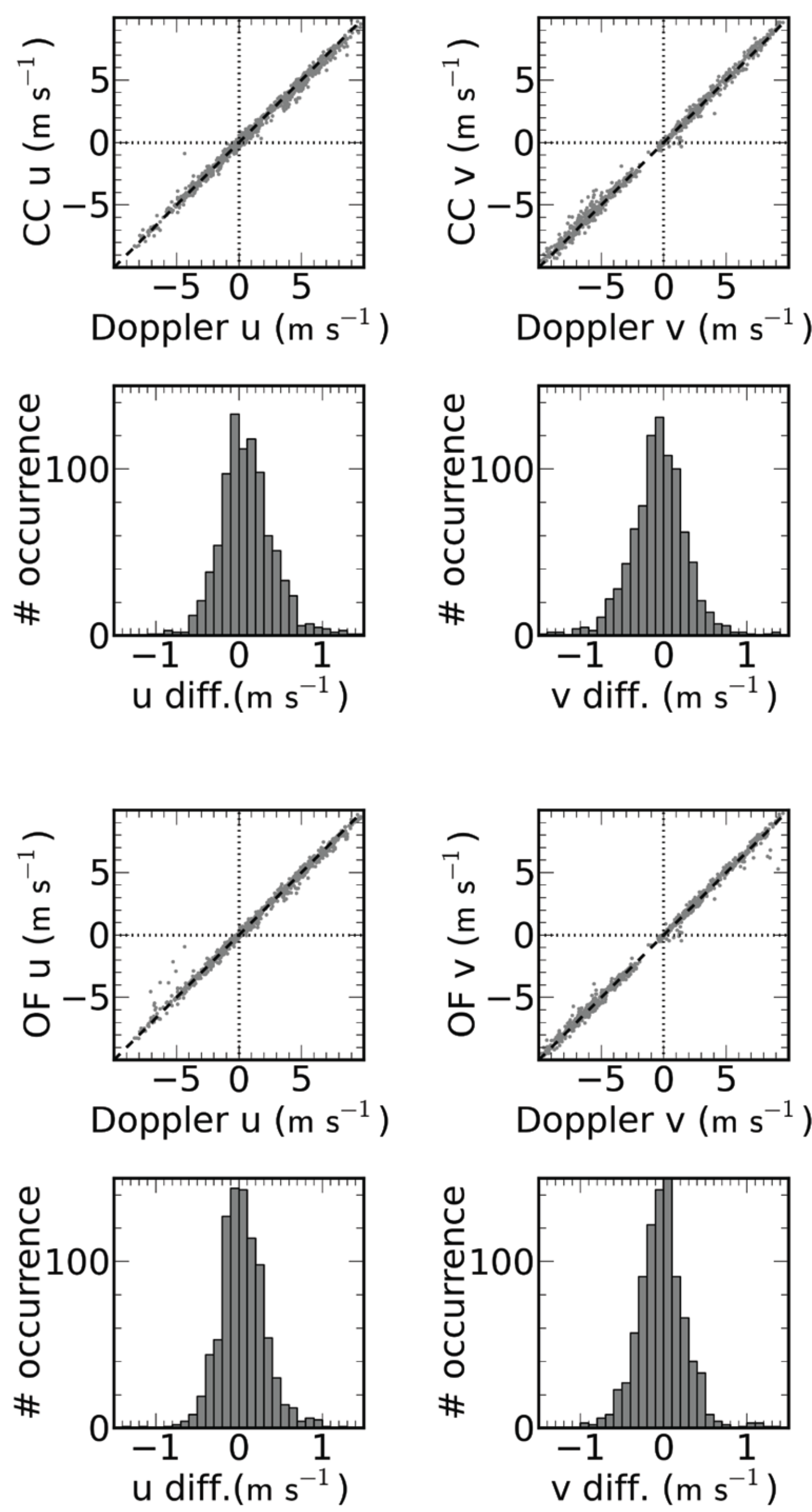
Example of **aerosol backscatter** and **estimated wind field**



Example of **time-series of wind speed and direction at 100 m AGL**,
Doppler (blue), cross-correlations (green), optical flow (orange),
instantaneous values (+ markers) and 10-min rolling mean (solid lines)



Scatter plot and differences
for the **10-min means**
over 15 days



Statistics computed from the 10-min means w.r.t. Doppler reference values
for components u, v over 15 days during Phase 1

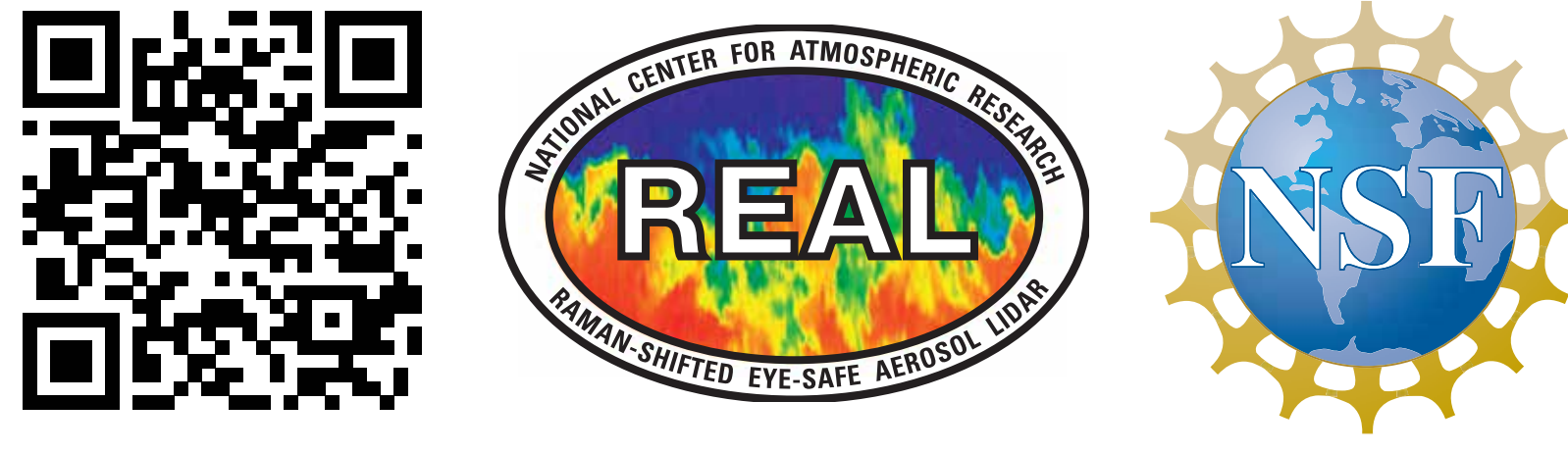
u	R ²	lin. reg. slope	lin. reg. offset (m/s)	Nb. points	% recovery
Cross-correl.	0.993	0.974	-0.050	891	99.0
Optic flow	0.993	0.980	0.007	892	99.1

v	R ²	lin. reg. slope	lin. reg. offset (m/s)	Nb. points	% recovery
Cross-correl.	0.995	0.992	0.061	891	99.0
Optic flow	0.996	0.995	0.010	892	99.1

Cross Correlations

Wavelet-based Optical Flow

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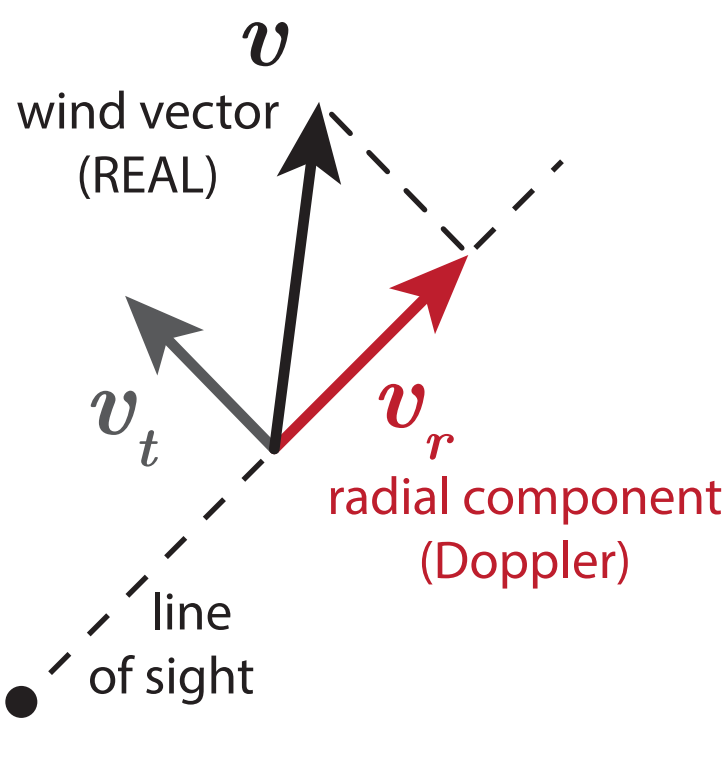
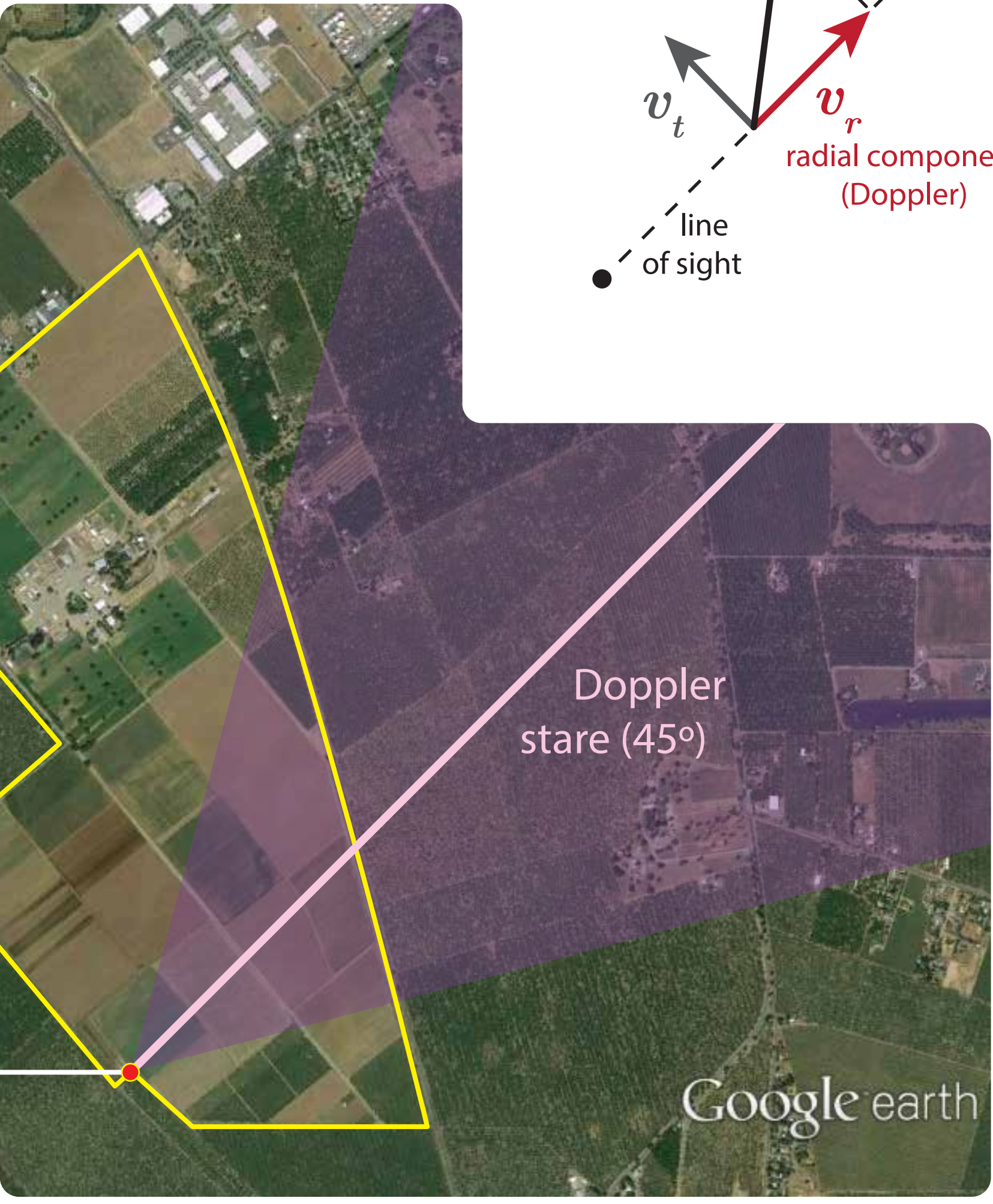


Phase 2: Spatial Validation

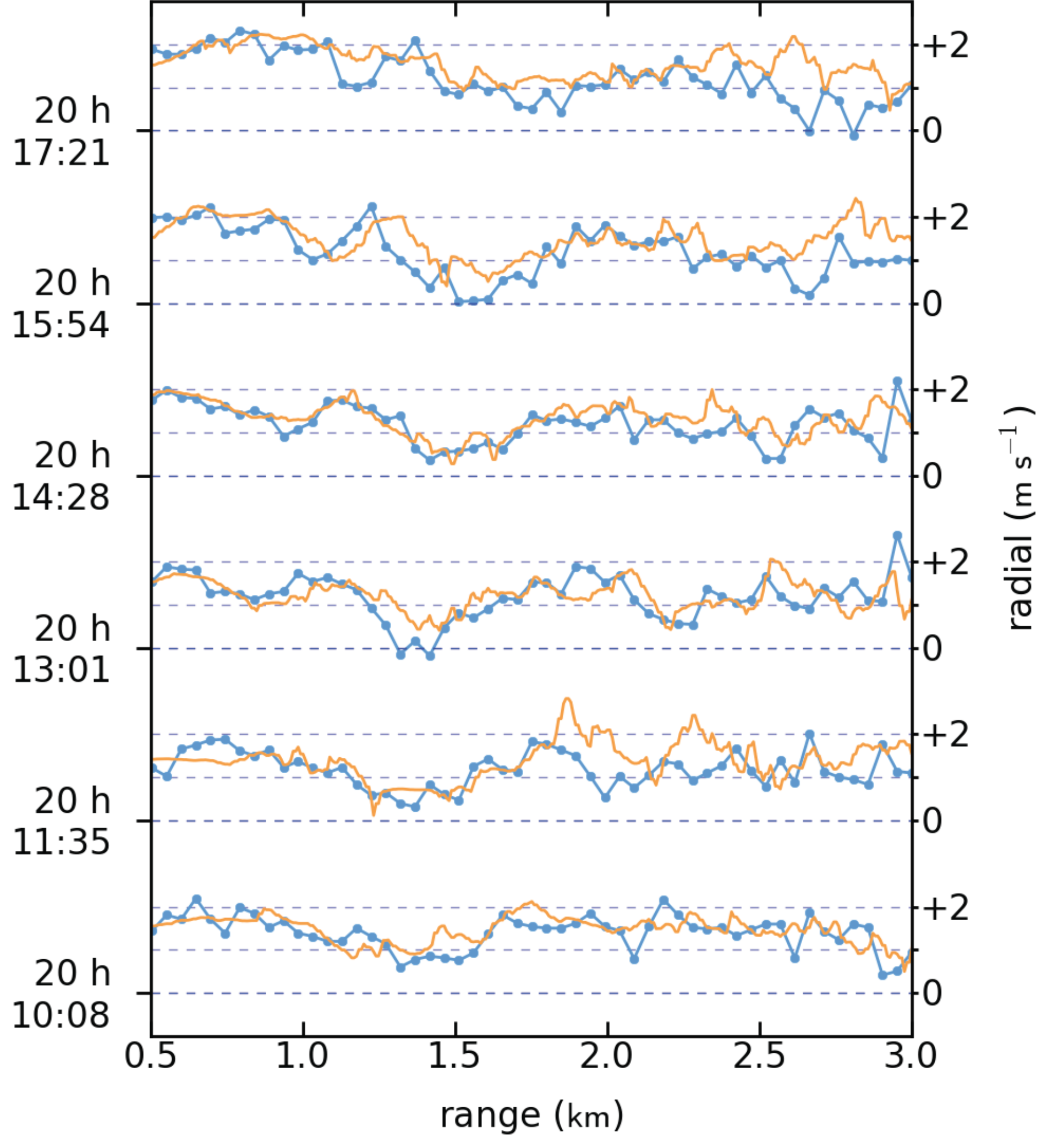
November 26, 2013 to January 15, 2014

During this phase of the experiment, the **Doppler lidar** was **installed on the roof of the REAL** container and operated in a **staring mode, horizontally**, at 45  azimuth. As such, it measured the **radial component of wind velocity only**.

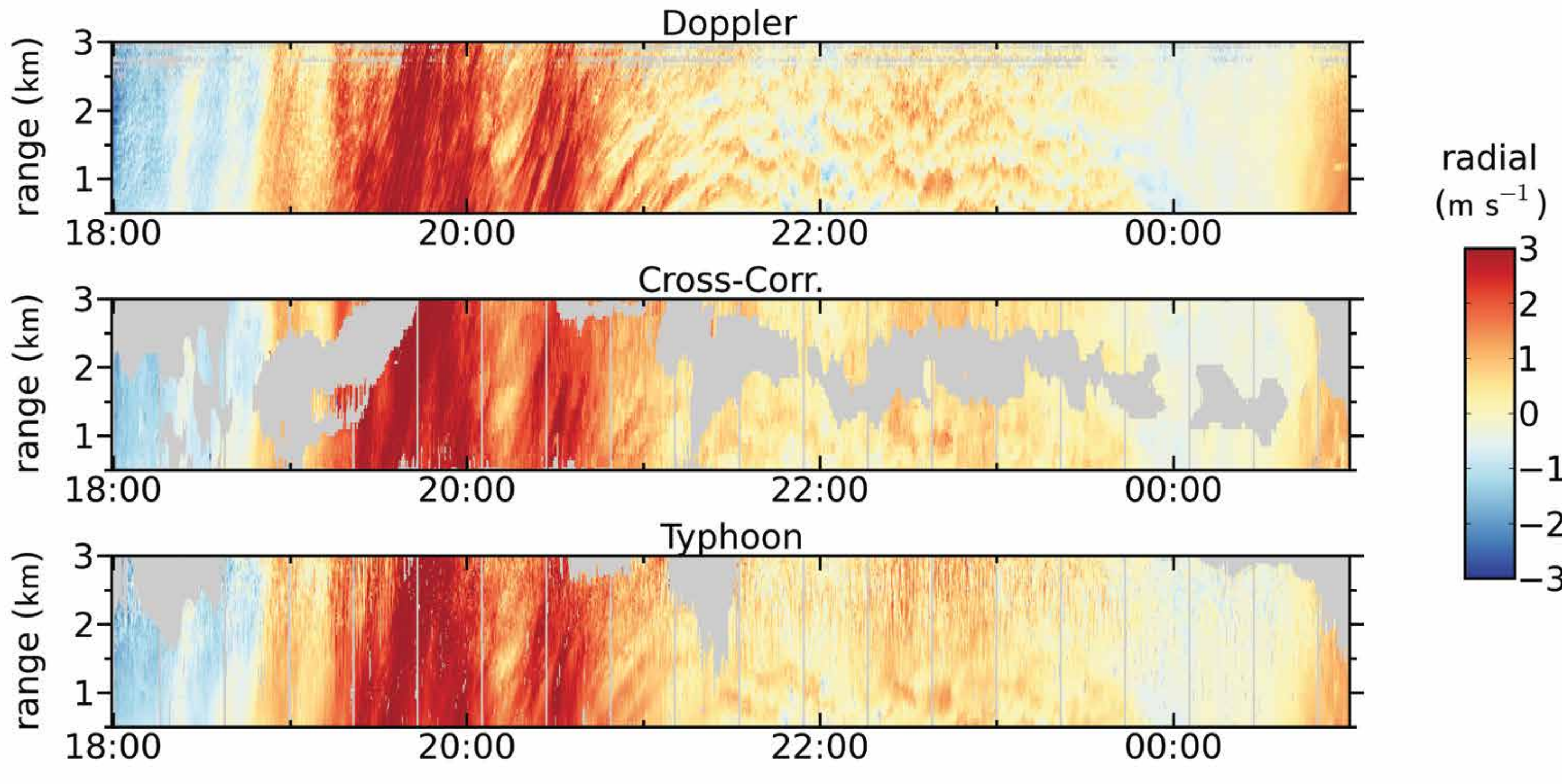
The corresponding radial component is derived from the 2-component wind fields estimated by the REAL for validation. This is the first time such a comparison is attempted.



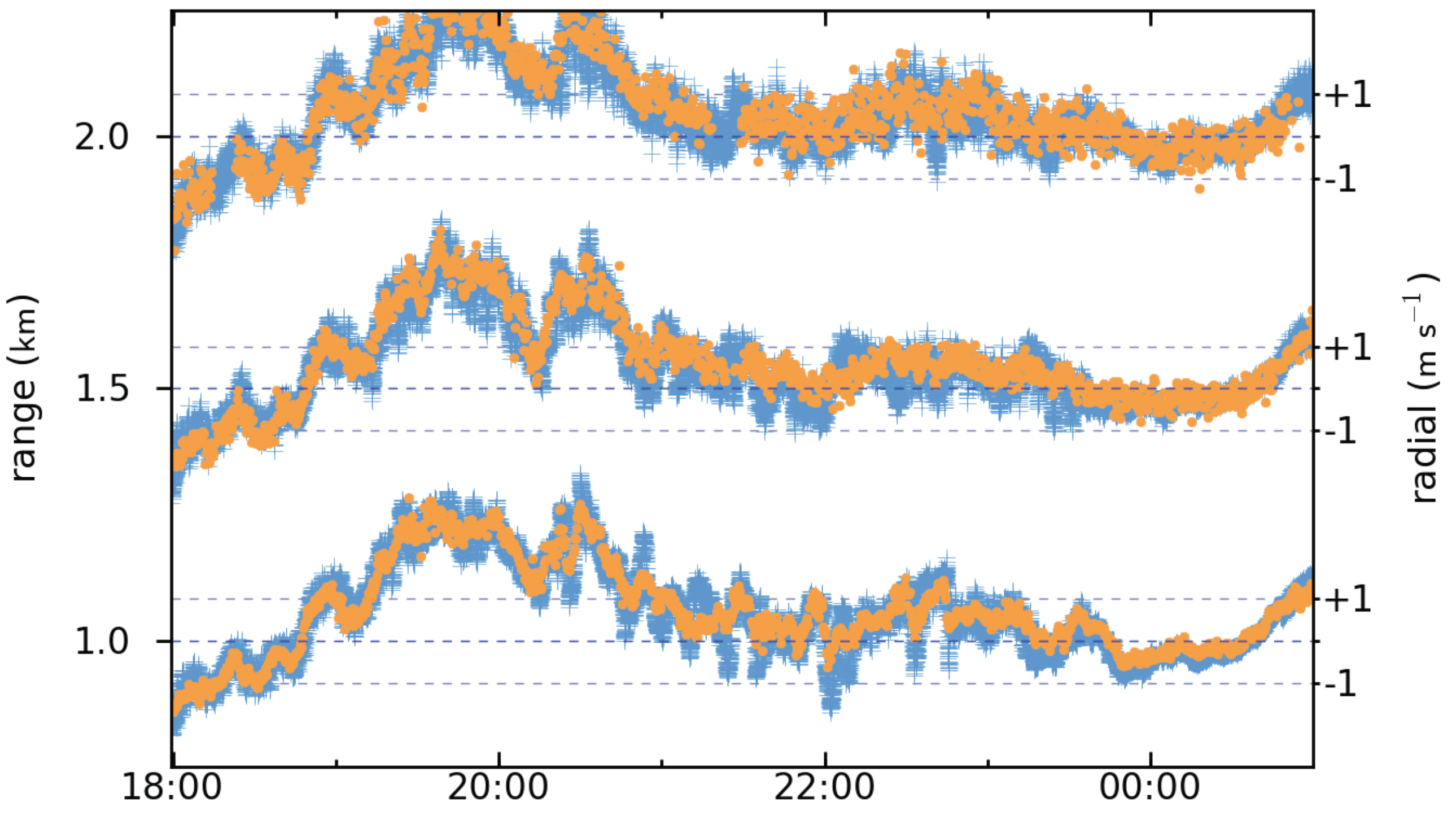
Radial velocity along the range
at different times
for the **Doppler** (blue) and **optical flow** (orange)



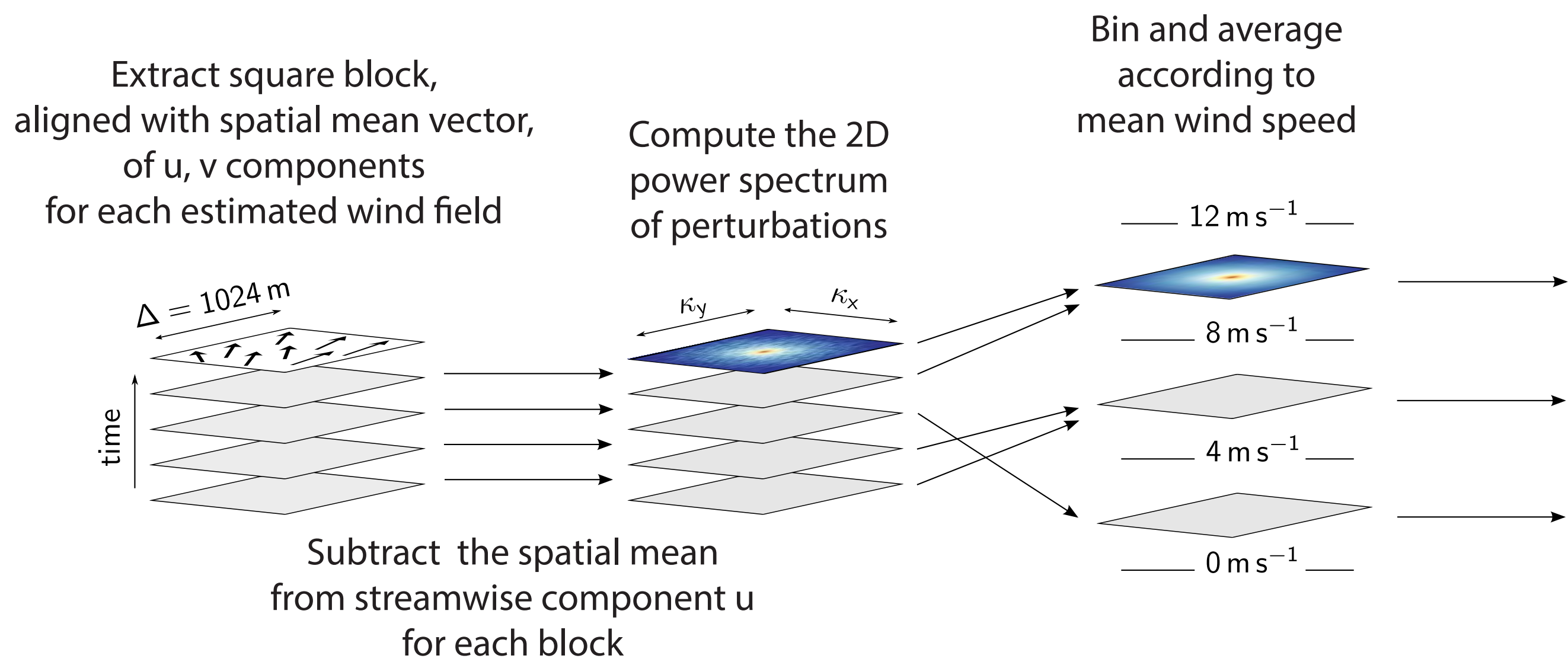
Series of radial velocity
as a function of time (horizontal) and range (vertical axis)



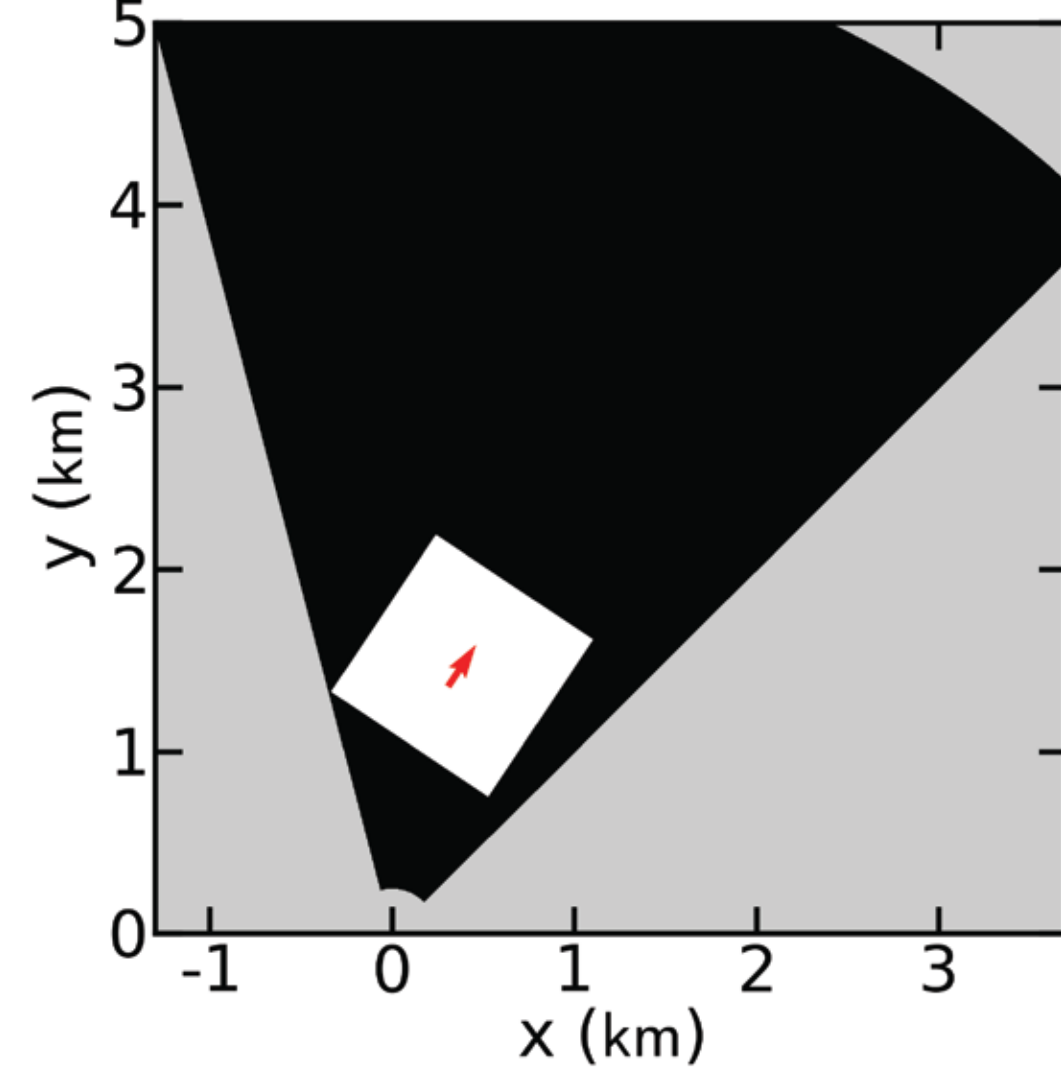
Time-series of radial velocity at different ranges
for the **Doppler** (blue) and **optical flow** (orange)



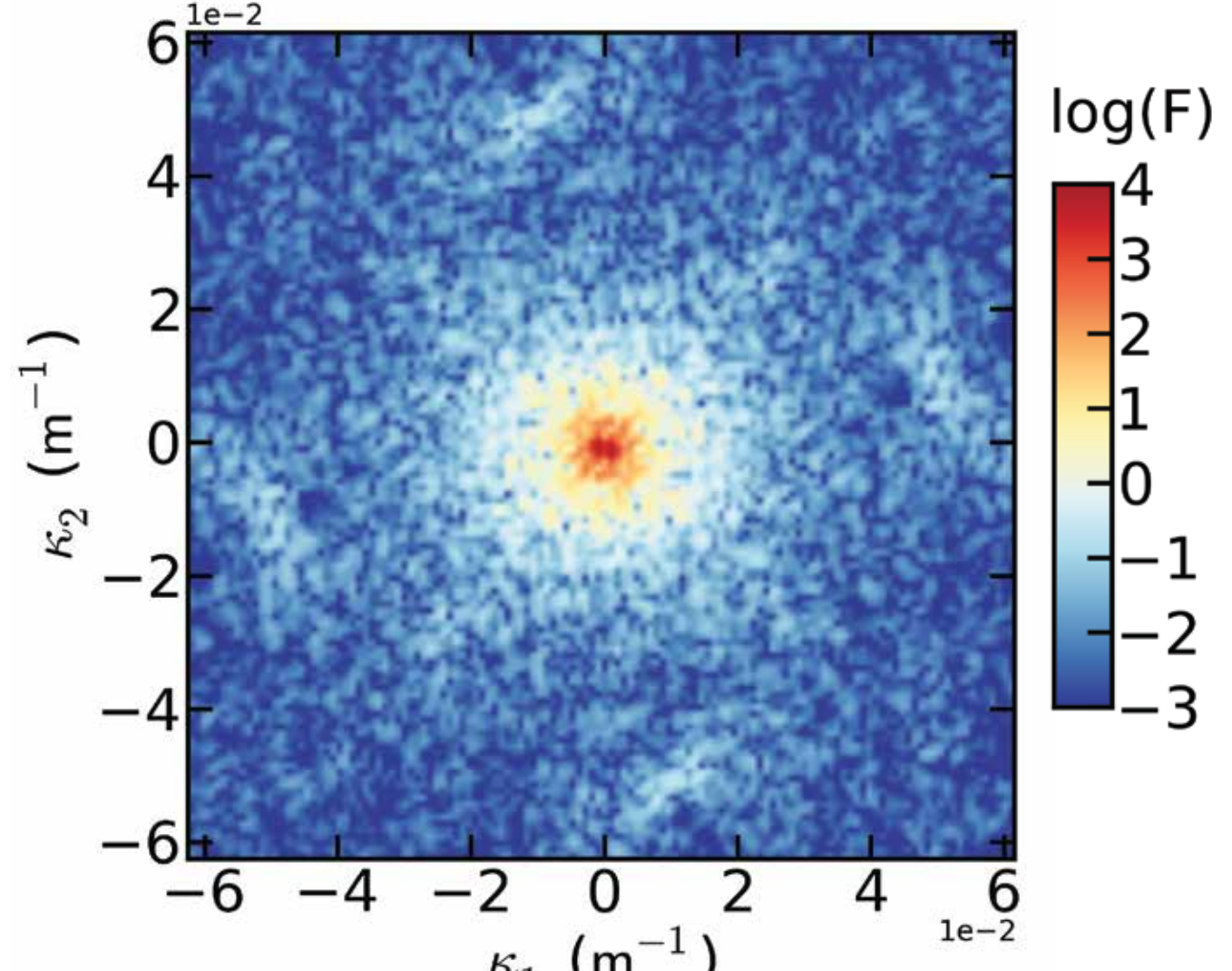
Spatial Power Spectra



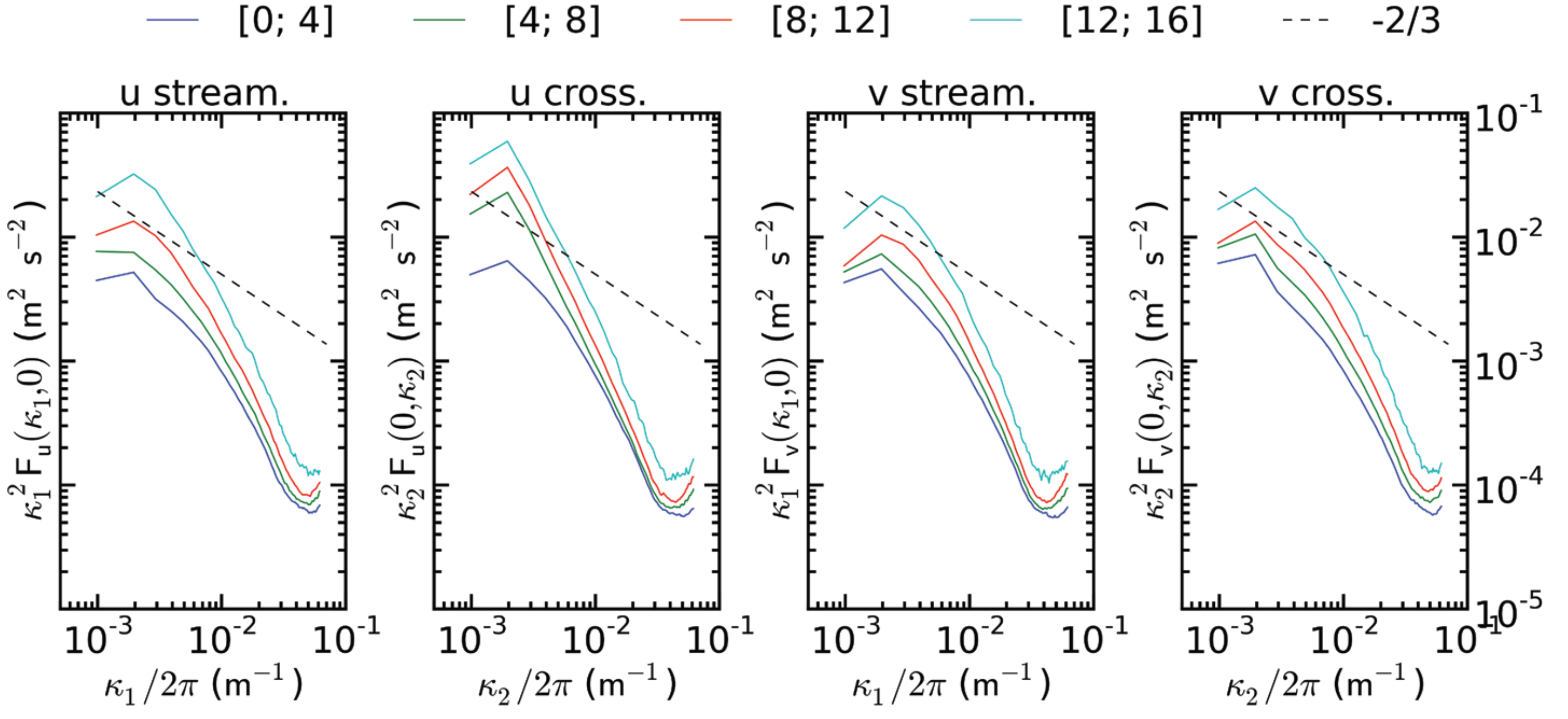
Location of the ~1x1 km block
(128x128 pixels at 8m/pixel)
rotating around (382, 1474) m



Example of 2D power spectrum
of spatial perturbations



Slices of the 2d spectra
in $k_2=0$ (streamwise) and $k_1=0$ (crosswise)
for components u (streamwise) and v (crosswise)
averaged according to mean wind speed (m s^{-1})



A total of 30 092 wind fields were used,
of which 36%, 34%, 28% and 2% contribute to each
of the above wind speed bins, respectively.

Acknowledgments

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References

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